

**U.G. 6th Semester Examination 2022**

**PHYSICS (Honours)**

**Paper Code : DSE 3 - A & B**

Full Marks : 32

Time : Two Hours

*The figures in the margin indicate full marks.  
Candidates are required to give their answers  
in their own words as far as practicable.*

**DSE 3 - A**

**(Advanced Mathematical Methods - II)**

1. Answer any six questions : 2×6=12
- (a) Prove that  $S_q^p$  is a mixed tensor of the second rank.
  - (b) Show that contraction of the tensor  $A_q^p$  is a scalar or invariant.
  - (c) Show that every tensor can be expressed as the sum of two tensors, one of which is symmetric and the other skew-symmetric in a pair of covariant and contravariant indices.
  - (d) Show that an  $n \times n$  orthogonal matrix has  $n(n-1)/2$  independent parameters.
  - (e) Show that  $Su(n)$  is a group.
  - (f) Show that the unit element in a group is unique.
  - (g) If ' $L$ ' is a Lie algebra such that  $\dim(L) = 3$  and  $\dim(L') = 2$ , then show that  $L'$  is abelian.
  - (h) Let  $G$  have a subgroup  $H$  and suppose that  $G/H$  is infinite cyclic. Prove that  $H$  is direct summand of  $G$ .
  - (i) Let  $G = A \oplus B$  and let  $H$  be the subgroup containing  $A$ . Prove that  $H = A \oplus (B \cap H)$ .

[P.T.O.]

2. Answer any *four* questions :

5×4=20

- (a) If  $ds^2 = g_{ij} dx^i dx^j$  is invariant, show that  $g_{ij}$  is a symmetric covariant tensor of rank 2. 5
- (b) If  $\phi = a_{jk} A^j A^k$  show that one can always express  $\phi = b_{jk} A^j A^k$  where  $b_{jk}$  is symmetric. 5
- (c) If  $A^\mu$  and  $B_\mu$  are any two vectors, then prove that  $A^\mu B_\mu$  is invariant. 5
- (d) Show that the Pauli matrices are the generators of  $Su(2)$ . 5
- (e) Show that the rotation about z-axis forms a subgroup of  $SO(3)$  5
- (f) If  $H$  &  $K$  be subgroups of  $G$  and  $x, y \in G$  with  $Hx = Ky$  then show that  $H = K$ . 5
- (g) Write down the properties of Lie group. What is the dimensions of a Lie group ? 4+1
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**DSE 3 - B****(Classical Dynamics)**

1. Answer any *six* questions : 2×6=12

(a) What do you mean by ‘generalised co-ordinates’ of a dynamical system ?

A particle is constrained to move on the surface of a sphere. Find the generalised co-ordinates in this case. 1+1

(b) Define a ‘cyclic coordinate’. The Lagrangian for a projectile moving under gravity is given by

$L = \frac{1}{2}m(\dot{x}^2 + \dot{y}^2 + \dot{z}^2) - mgz$ , symbols being usual. Identify the cyclic coordinates, if any. 1+1

(c) Prove that the isotropy of space leads to the conservation of angular momentum. 2

(d) Express Hamilton’s canonical equations in terms of Poisson’s brackets. 2

(e) Show that a generalised coordinate which is ignorable in Lagrangian is also ignorable in Hamiltonian of a system. 2

(f) Consider the following transformation :

$$Q = q \cos \alpha - p \sin \alpha \quad \text{and} \quad P = q \sin \alpha + p \cos \alpha ,$$

where  $q$  and  $p$  are the generalised position and conjugate momentum of the system respectively. Prove that the Poisson bracket  $[Q, P] = 1$  for any values of  $\alpha$ . 2

(g) What do you mean by space like and time-like four vectors ? 2

(h) The Lagrangian of a free particle moving in a three-dimensional space is given by

$L = \frac{1}{2}m(\dot{x}^2 + \dot{y}^2 + \dot{z}^2)$ , terms being usual. Prove that the Hamiltonian of the particle is also given by the same expression. 2

(i) What is Reynold’s number ? What is its importance in the study of fluid motion ? 1+1

2. Answer any *four* questions : 5×4=20

(a) A simple pendulum of fixed length ‘ $l$ ’ and bob mass ‘ $m$ ’ is oscillating in the vertical plane. Taking the angular displacement ( $\theta$ ) as the generalised coordinate, show that the corresponding Lagrange’s equation would be

[P.T.O.]

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$$\ddot{\theta} + \frac{g}{l}\theta = 0$$

Also estimate the Hamiltonian of the pendulum. 4+1

- (b) A particle is moving in a plane under a central attractive inverse square force. Write down its Lagrangian and derive its equation of motion.

Prove that the areal velocity of such particle remains constant. 3+2

- (c) Show that Lagrange's equation of motion remains unaltered if the Lagrangian  $L(q, q', t)$

is added with the total time derivative  $\frac{d\phi}{dt}$ , where  $\phi = \phi(q, t)$ .

What is the familiar name of the function '  $\phi$  ' ? 4+1

- (d) The Lagrangian of a system is given by  $L = \frac{1}{2}\alpha\dot{q}^2 - \frac{1}{2}\delta q^2$ , where  $\alpha$  and  $\delta$  are constants.

(i) Obtain the equation of motion.

(ii) Find the Hamiltonian of the system. 3+2

- (e) (i) If the Lagrangian of a system does not depend on time explicitly, show its Hamiltonian remains conserved.

(ii) For a system and Hamiltonian  $H$ , show that

$$\frac{dF}{dt} = \frac{\partial F}{\partial t} + [F, H], \text{ where } F = F(q, p, t) \text{ and } [F, H] \text{ represents a Poisson bracket.}$$

3+2

- (f) What is Doppler effect ? Derive an expression for relativistic Doppler effect using four vector concepts. 1+4

- (g) Derive the expression for equation of continuity for a fluid. Hence show that for irrotational flow of incompressible fluid, the velocity potential satisfies the Laplace equation. 3+2

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